### **Diverse Near Neighbor Problem**

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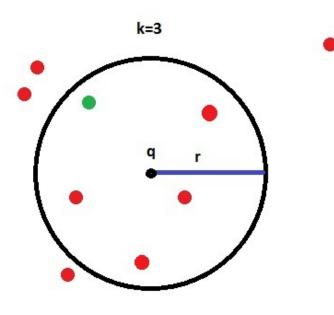
# Near Neighbor Problem

### • Definition

- Set of n points P in d-dimensional space
- Query point *q*
- Report one neighbor of *q* if there is any
- **Neighbor:** A point within distance *r* of query

### Application

- Major importance in databases (document, image, video), information retrieval, pattern recognition
  - Object of interest as point
  - Similarity is measured as distance.



## Motivation

#### Search: How many answers?

- Small output size, e.g. 10
  - Reporting k Nearest Neighbors may not be informative (could be identical texts)
- Large output size
  - Time to retrieve them is high

#### Small output size which is

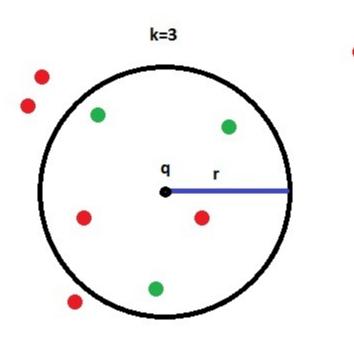
- Relevant and Diverse
- Good to have result from each cluster, i.e. should be diverse



# **Diverse Near Neighbor Problem**

### • Definition

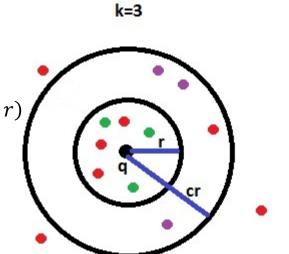
- Set of n points P in d-dimensional space
- Query point q
- Report the k most diverse neighbors of q
- Neighbor:
  - Points within distance r of query
  - We use Hamming distance
- Diversity:
  - $\operatorname{div}(S) = \min_{p,q \in S} |p q|$
- Goal: report Q (green points), s.t.
  - $Q \subseteq P \cap B(q,r)$
  - |Q| = k
  - div(Q) is maximized



# Approximation

- Want sublinear query time, so need to approximate
- Approximate NN:
  - $B(q,r) \rightarrow B(q,cr)$  for some value of c > 1
  - **Result:** query time of  $O(dn^{\frac{1}{c}})$
- Approximate Diverse NN:
  - Bi-criterion approximation: distance and diversity
  - (**c**,  $\alpha$ )-Approximate k-diverse Near Neighbor
  - Let  $Q^*$  (green points) be the optimum solution for B(q, r)
    - Report approximate neighbors Q (purple points)  $Q \subseteq B(q, cr)$
    - Diversity approximates the optimum diversity

 $div(Q) \ge \frac{1}{\alpha} div(Q^*), \alpha \ge 1$ 



## Results

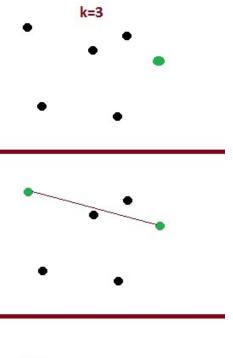
	Algorithm A	Algorithm B
Distance Apx. Factor	c > 2	c >1
Diversity Apx. Factor $\alpha$	6	6
Space	$(n\log k)^{1+1/(c-1)} + nd$	$\log k * n^{1+1/c} + nd$
Query Time	$\left(k^2 + \frac{\log n}{r}\right) d (\log k)^{c/(c-1)} n^{1/(c-1)}$	$\left(k^2 + \frac{\log n}{r}\right)d * \log k * n^{1/c}$

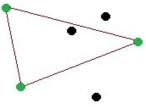
• Algorithm A was earlier introduced in [Abbar, Amer-yahia, Indyk, Mahabadi, WWW'13]

### Techniques

# Compute k-diversity: GMM

- Have n points, compute the subset with maximum diversity.
- Exact : **NP-hard** to approximate better than 2 [Ravi et al.]
- GMM Algorithm [Ravi et al.] [Gonzales]
  - Choose an arbitrary point
  - Repeat k-1 times
    - Add the point whose minimum distance to the currently chosen points is maximized
- Achieves approximation factor 2
- Running time of the algorithm is O(kn)

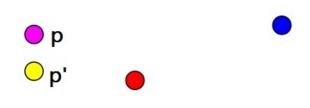


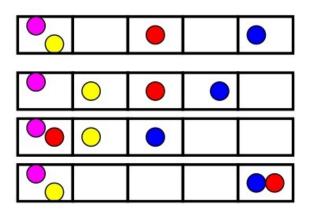


# Locality Sensitive Hashing (LSH)

### • LSH

- close points have higher probability of collision than far points
- Hash functions:  $g_1$  , ... ,  $g_L$ 
  - $g_i = \langle h_{i,1}, \dots, h_{i,t} \rangle$
  - $h_{i,j} \in \mathcal{H}$  is chosen randomly
  - $\mathcal{H}$  is a family of hash functions which is  $(P_1, P_2, r, cr)$ -sensitive:
    - If  $||p p'|| \le r$  then  $\Pr[h(p) = h(p')] \ge P_1$
    - If  $||p p'|| \ge cr$  then  $\Pr[h(p) = h(p')] \le P_2$
  - Example: Hamming distance:
    - $h(p) = p_i$  , i.e., the ith bit of p
    - Is  $(1 \frac{r}{d}, 1 \frac{rc}{d}, r, rc)$ -sensitive
- L and t are parameters of LSH





# LSH-based Naïve Algorithm

- [Indyk, Motwani] Parameters *L* and *t* can be set s.t. With constant probability
  - Any neighbor of q falls into the same bucket as q in at least one hash function
  - Total number of **outliers** is at most 3L
  - **Outlier** : point farther than *cr* from the query point

#### Algorithm

- Arrays for each hash function  $A_1, \dots, A_L$
- For a query *q* compute
  - Retrieve the possible neighbors  $S = \bigcup_{i=1}^{L} A[g_i(q)]$
  - Remove the outliers  $S = S \cap B(q, cr)$
  - Report the approximate k most diverse points of S, or GMM(S)
- Achieves (c,2)-approximation
- Running time may be linear in n  $\otimes$ 
  - Should prune the buckets before collecting them

### Core-sets

S'

S

- **Core-sets** [Agarwal, Har-Peled, Varadarajan]**:** subset of a point set **S** that represents it.
  - Approximately determines the solution to an optimization problem
  - Composes: A union of coresets is a coreset of the union
- $\beta$  core-set: Approximates the cost up-to a factor of  $\beta$
- Our Optimization problem:
  - Finding the k-diversity of S.
  - Instead we consider finding K-Center Cost of S
    - $KC(S,S') = \max_{p \in S} \min_{p' \in S'} |p p'|$

• 
$$KC_k(S) = \min_{S' \subseteq S, |S'|=k} KC(S, S')$$

- KC cost 2-approximates diversity
  - $KC_{k-1}(S) \le div_k(S) \le 2.KC_{k-1}(S)$
- **GMM** computes a 1/3-Coreset for KC-cost

### Algorithms

# Algorithm A

- Parameters *L* and *t* can be set s.t. with constant probability
  - Any neighbor of q falls into the same bucket as q in at least one hash function
  - There is no outlier
- No need to keep all the points in each bucket,
- just keep a coreset!
  - $A'_{i}[j] = GMM(A_{i}[j])$
  - Keep a 1/3 coreset of  $A_i[j]$





- Given query **q** 
  - Retrieve the coresets from buckets  $S = \bigcup_{i=1}^{L} \mathbf{A}'[g_i(q)]$
  - Run GMM(S)
  - Report the result

# Analysis

- Achieves (c,6)-Approx
  - Union of 1/3 coresets is a 1/3 coreset for the union
  - The last GMM call, adds a 2 approximation factor
- **Only works** if we set *L* and *t* s.t. there is **no outlier** in *S* with constant probability
  - Space:  $O(nL) = O((n \log k)^{1+1/(c-1)} + nd)$

- Time: 
$$O(Lk^2) = O(\left(k^2 + \frac{\log n}{r}\right)d (\log k)^{c/(c-1)}n^{1/(c-1)})$$

- Only makes sense for c > 2
- Not optimal:
  - ANN query time is  $O(dn^{\frac{1}{c}})$
  - So if we want to improve over these we should be able to deal with outliers.

## Robust Core-sets

- S' is an l-robust  $\beta$ -coreset for S if
  - for any set O of outliers of size at most l
  - $(S' \setminus O)$  is a  $\beta$ -coreset for S
- Peeling Algorithm [Agarwal, Har-peled, Yu,'06][Varadarajan, Xiao, '12]:
  - Repeat (l+1) times
    - Compute a β-coreset for *S*
    - Add them to the coreset *S*'
    - Remove them from the set *S*

Note: if we order the points in S' as we find them, then the first (l' + 1)k points also form an l'-robust  $\beta$ -coreset.

k=2, I=2 • 7 20 3 20

2 robust coreset: S'= {3, 5; 2, 9; 1, 6}

1 robust coreset

# Algorithm B

- Parameters *L* and *t* can be set s.t. With constant probability
  - Any neighbor of q falls into the same bucket as q in at least one hash function
  - Total number of **outliers** is at most 3L
- For each bucket  $A_i[j]$  keep an 3L-robust 1/3-coreset in  $A'_i[j]$  which has size (3L + 1)k
- For query *q* 
  - For each bucket  $A'[g_i(q)]$ 
    - Find smallest l s.t. the first (kl) points contains less than l outliers
    - Add those *kl* points to *S*
  - Remove outliers from S
  - Return GMM(S)

### **Example and Analysis**







- Total # outliers  $\leq 3L$ , |S| < O(Lk)
- Time:  $O(Lk^2) = O(\left(k^2 + \frac{\log n}{r}\right)d * \log k * n^{\frac{1}{c}})$
- Space:  $O(nL) = O(\log k * n^{1+1/c} + nd)$
- Achieves (c,6)-Approx for the same reason

## Conclusion

	Algorithm A	Algorithm B	ANN
Distance Apx. Factor	c > 2	c >1	c >1
Diversity Apx. Factor α	6	6	-
Space	$\sim n^{1+\frac{1}{c-1}}$	$\sim n^{1+\frac{1}{c}}$	$n^{1+\frac{1}{c}}$
Query Time	$\sim d n^{\frac{1}{c-1}}$	$\sim d n^{\frac{1}{c}}$	$d n^{\frac{1}{c}}$

### **Further Work**

- Improve diversity factor α
- Consider other definitions of diversity , e.g., sum of distances

### Thank You!